

I-95 Corridor Coalition's Vehicle Probe Project

# **A cross-vendor and cross-state analysis of the GPS-probe data latency**



**Transportation Research Board  
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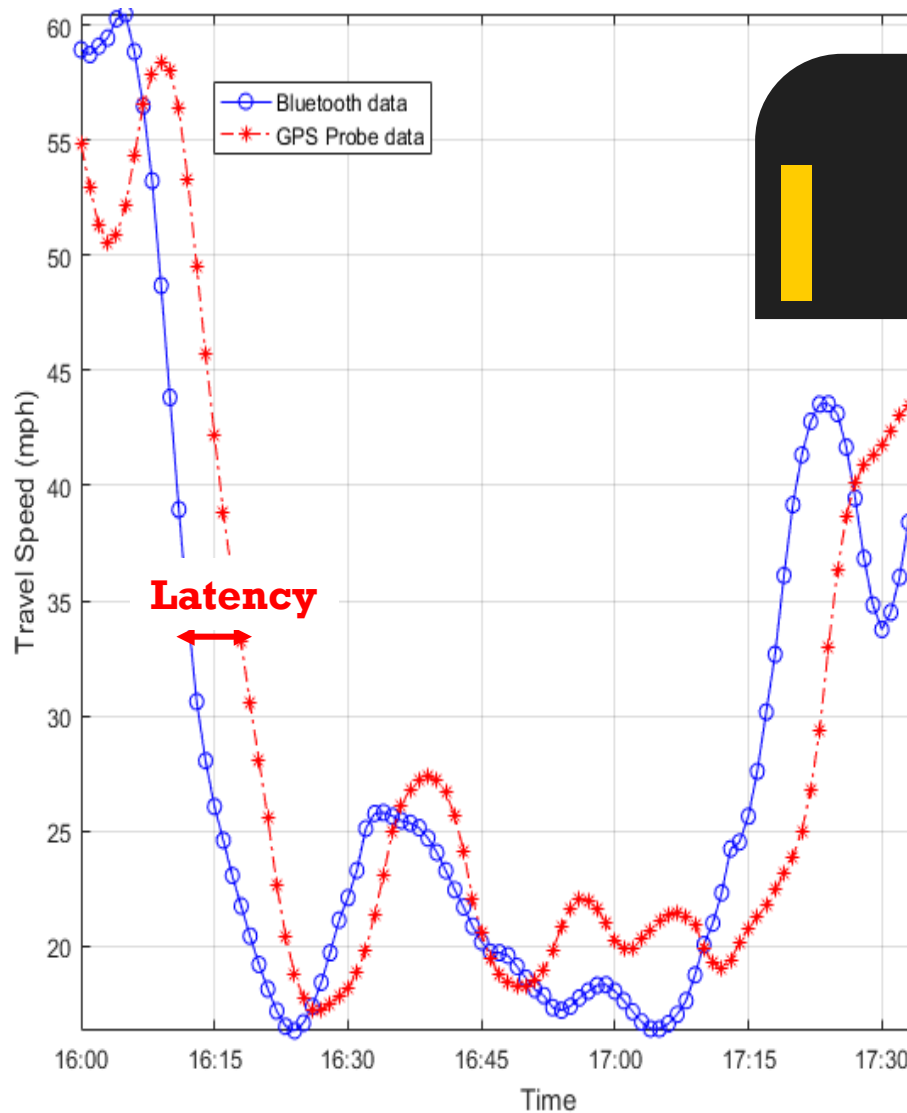


**I-95 CORRIDOR  
COALITION**



Masoud Hamed<sup>i\*</sup> | Zhongxiang Wang  
Elham Sharifi | Stanley Young

Jan 8<sup>th</sup> 2018

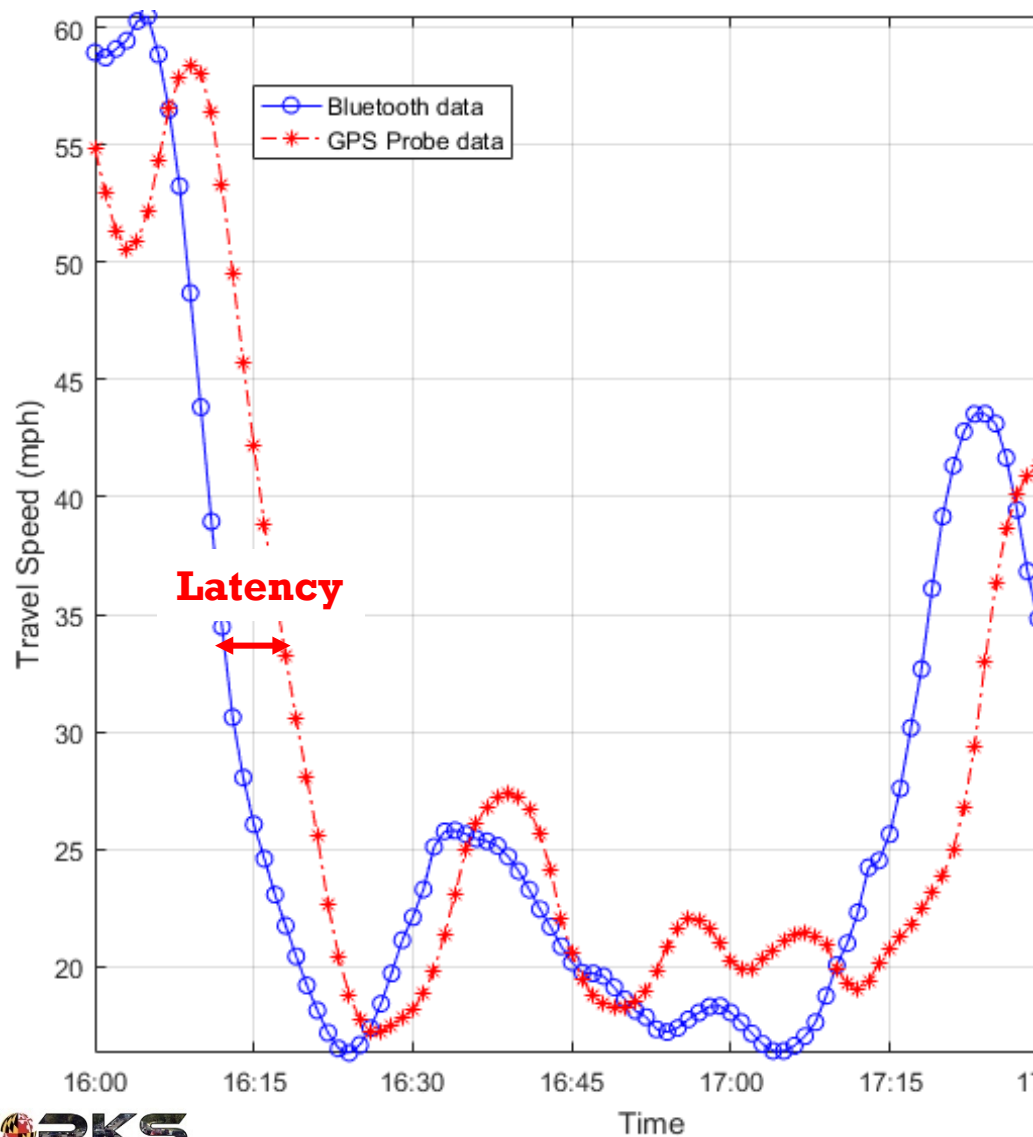


# OUTLINE

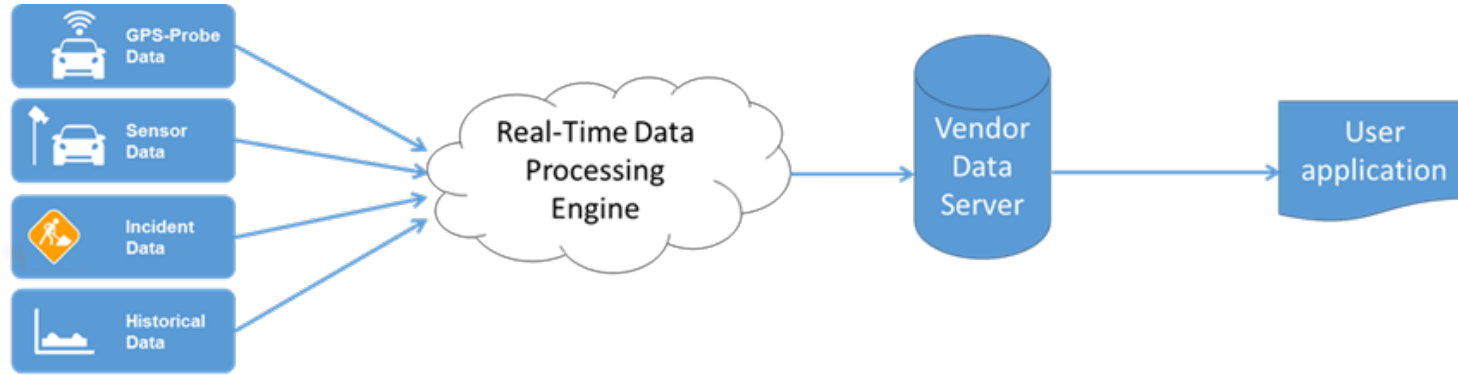
1. INTRODUCTION
2. LITERATURE REVIEW
3. METHODOLOGY
4. CASE STUDY
5. CONCLUSIONS

# What is Latency?

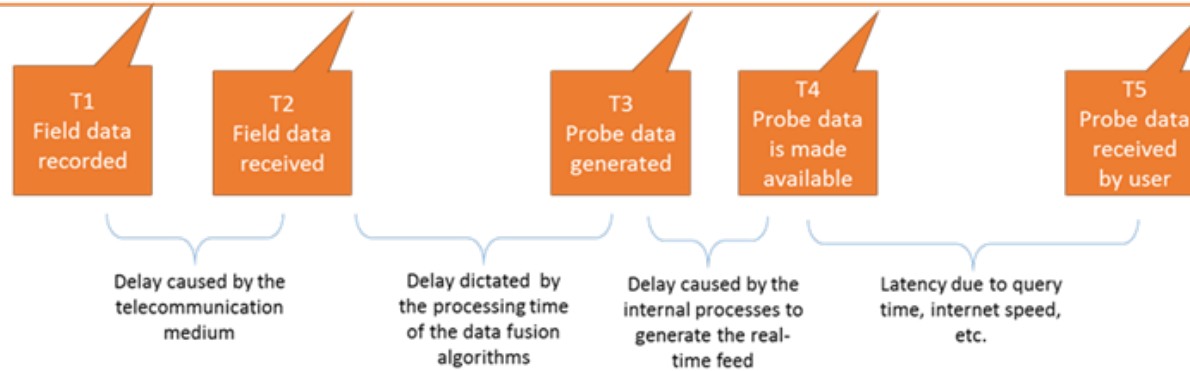
- **LATENCY** is the time difference between GPS-probe data and real traffic condition;
- It describes the punctuality of data;
- It is crucial to real-time applications.



# Where does the latency come from?

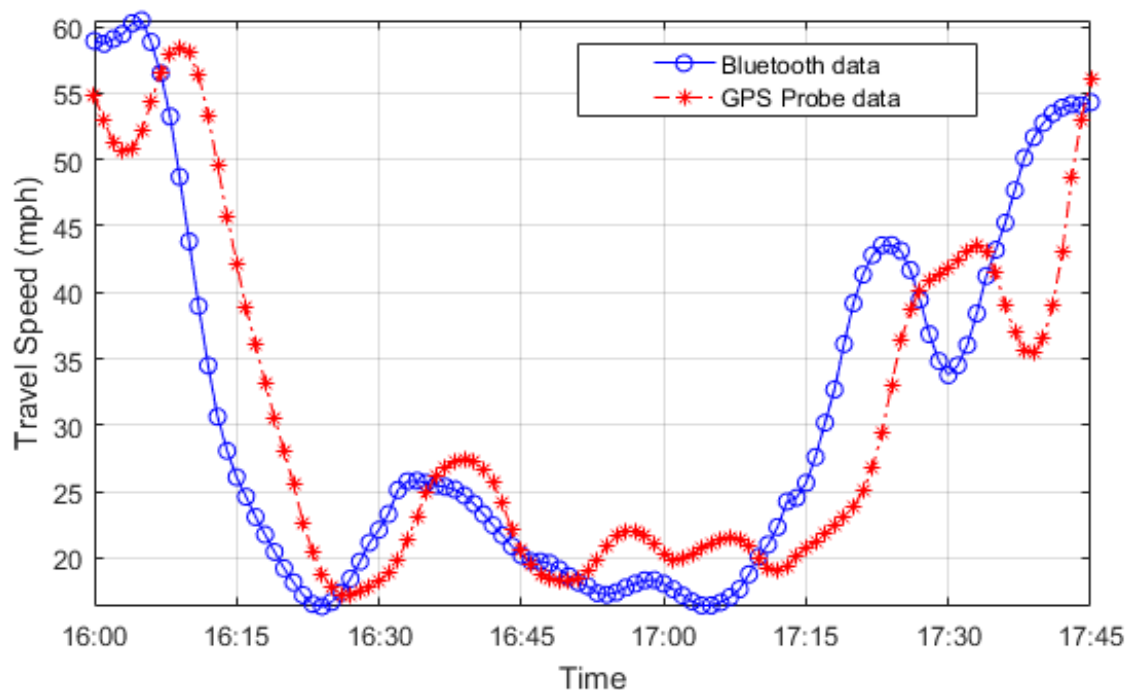


## Timeline



# Definition of Latency

Latency is defined as “the difference between the time the traffic flow is perturbed and the time that the change in speed is reflected in the data.”





## Related Research

- Kim, Seoungbum, and Benjamin Coifman. "Comparing INRIX speed data against concurrent loop detector stations over several months." *Transportation Research Part C: Emerging Technologies* 49 (2014): 59-72.
  - Objective: Maximizing Correlation Coefficient
  - Average latency : 6.8 minutes
  - Maximum latency could exceed 10 minutes in many time periods
    - Reference data: Loop detector
    - Aggregating data into 10 second time interval



## Related Research

- INRIX.(2007). Traffic Data and Associated Services along the I-95 Corridor
  - INRIX will deliver current speed, travel time, average speed...with latency on average of 4.5 minutes.
- Wang, Z., Hamed, M. and Young, S., 2017. A Methodology for Calculating Latency of GPS Probe Data. Transportation Research Record: Journal of the Transportation Research Board, No. 2645. DOI: 10.3141/2645-09.
  - Propose methodology to measure GPS-probe data latency in comparing to Bluetooth data. It is shown to be effective, but only on a limited dataset for one GPS-probe data vendor.

# Contributions

- ✓ **Applying the latency measurement methodology (Wang et. al 2017) to a larger dataset**
  - ✓ Expanding to three states
  - ✓ Data from three major probe data vendors
- ✓ **Developing a robust algorithm for automating slowdown episode detection**
- ✓ **Revisiting conclusions of the previous research based on the extended data set;**
- ✓ **Analyzing latency for different vendors to describe:**
  - Latency distribution for different vendors;
  - Latency distribution at slowdown and recovery periods;
  - Latency distribution at different times of the day;
  - Latency distribution for segments of various lengths;
  - Statistical comparison of latency across three vendors.





# Data Processing

## Bluetooth/WiFi data preparation

- Matching and filtering high resolution re-identification based travel time observations to generate segment space mean speed data;
- Aggregating reference data in one minute intervals.

## Data Filtering

**The following observations are identified and discarded:**

- Observations with unreasonably low or high speeds;
- Observations in a particular time interval that are far from the average of the rest of the speeds observed in the same time interval.

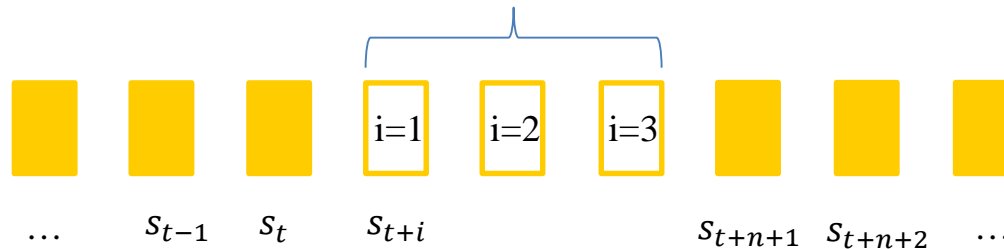
# Data Processing

## Data Interpolation

The average of the neighboring observations is considered as the travel speed for the missing interval (only applied to less than or equal to 5 mins).

$$s_{t+i} = s_t + \frac{i}{n+1} (s_{t+n+1} - s_t) \quad \forall i = 1, 2, 3$$

Missing Interval: n=3



# Data Processing

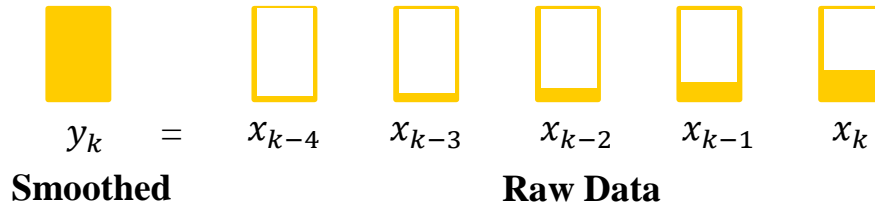
## Data Smoothing

### ❖ Weighted moving average function



Arithmetic growth of the weights with the previous five time intervals

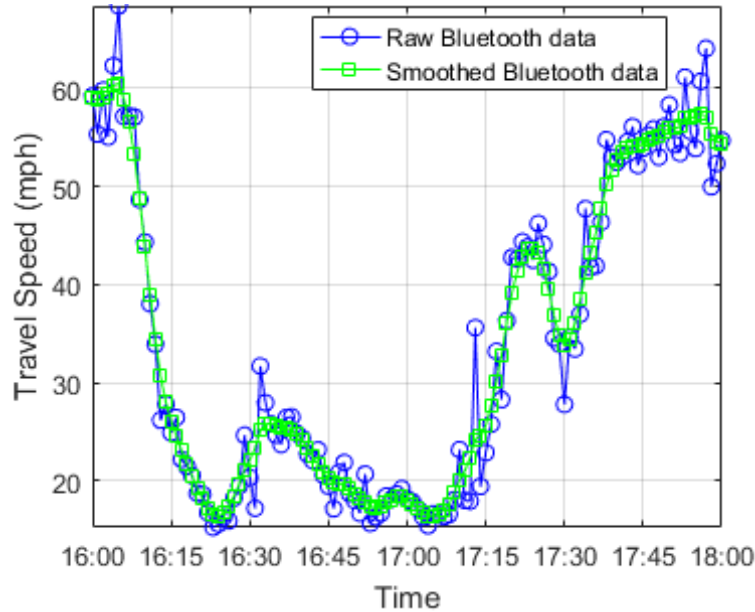
$$y_k = 0.33x_k + 0.27x_{k-1} + 0.20x_{k-2} + 0.13x_{k-3} + 0.07x_{k-4}$$



Why Zero-phase digital filtering? Smoothing may introduce undesired horizontal shift into the time series, however in *Zero-phase digital filtering*, forward shift is followed by a reverse shift, so the artificial shift is compensated.

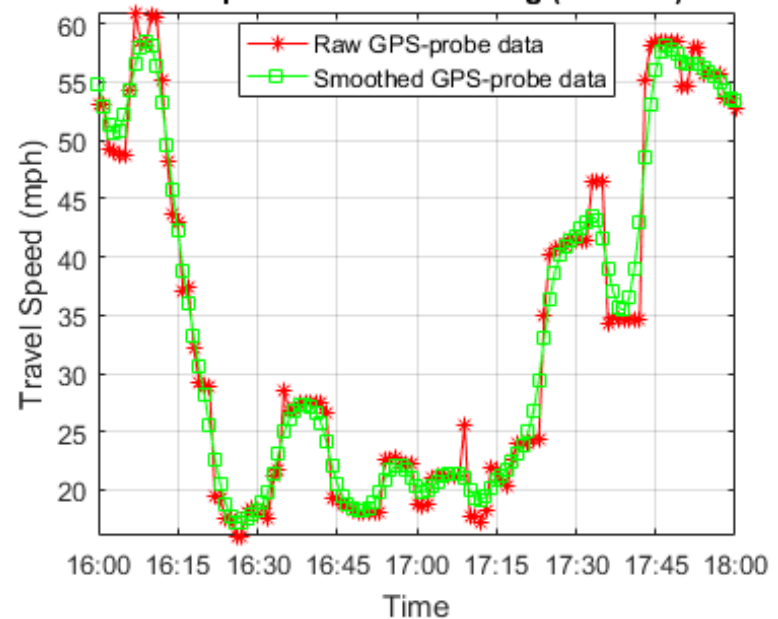
# Data Processing

## Data Smoothing



✓ **Less noise**

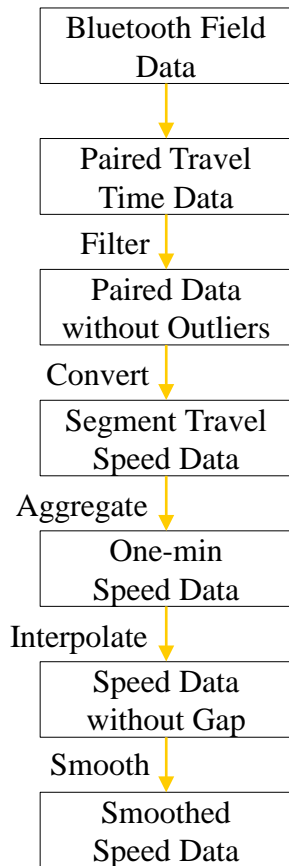
✓ **No shift**



# Data Processing

## Flow chart

### Bluetooth Data Processing



GPS-probe Data

Filter (rule out data with low confidence score)

Path data

Interpolate

GPS-probe Data without Gap

Smooth

Smoothed GPS-probe Data

### GPS-probe Data Processing

Calculating Latency

# Objective

- Find the shift distance that maximizes the overlapping of Bluetooth data and GPS-probe data.

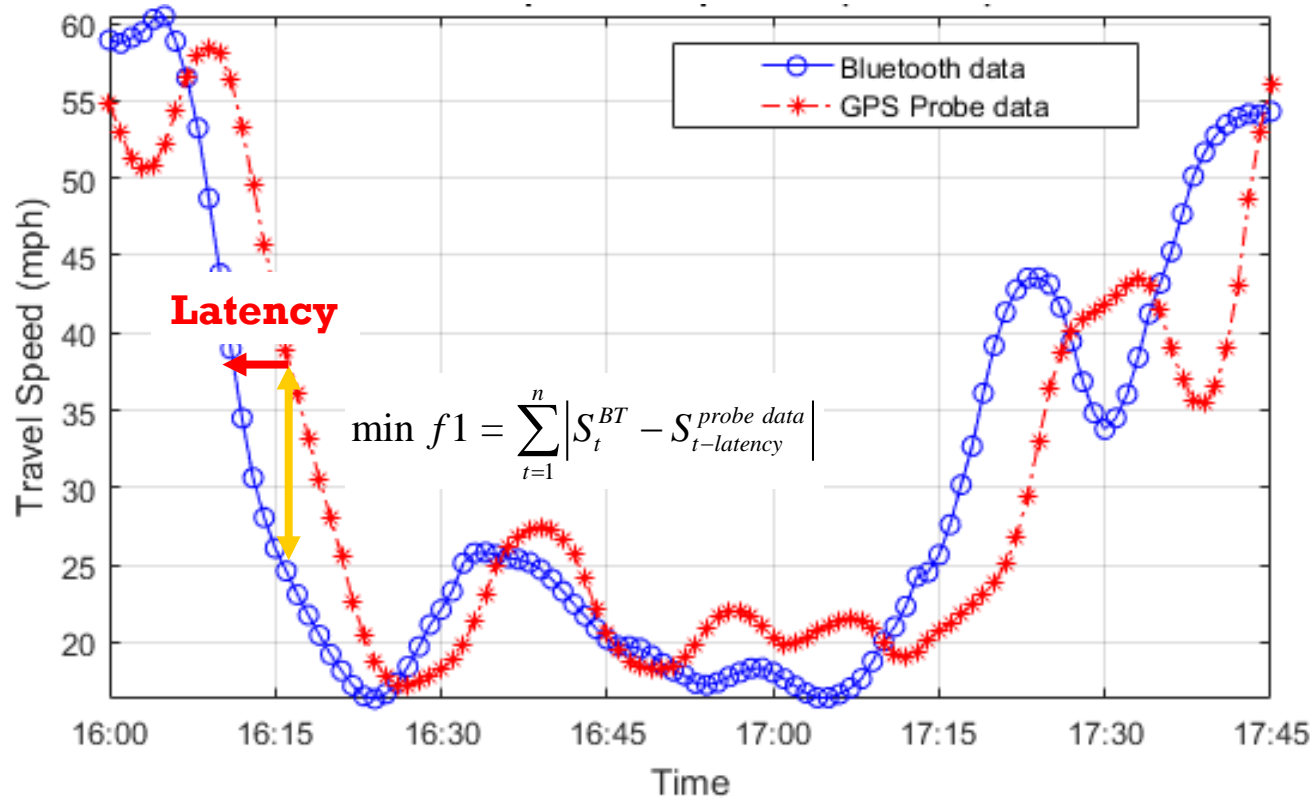
$$\min f1 = \sum_{t=1}^n |S_t^{BT} - S_{t-latency}^{probe\ data}| \quad \text{➤ (AVD) Absolute vertical distance between two curves}$$

$$\min f2 = \sum_{t=1}^n (S_t^{BT} - S_{t-latency}^{probe\ data})^2 \quad \text{➤ (SVD) Squared vertical distance, which gives more weights to the points that have bigger difference}$$

$$\min f3 = \text{corr}(S_t^{BT}, S_{t-latency}^{probe\ data}) \quad \text{➤ (COR) Statistical representation of the linear relationship between two curves}$$

$$lb \leq latency \leq ub$$

## Minimize Absolute Vertical Distance ( $f1$ ) – as example



# Data Selection

State	Road	Start Point	End Point	Length (mile)	Date
South Carolina	I-85	US-276/Exit 48	SC-14/Exit 56	7.15	12/03/2015
	I-26	Bush River Rd/Exit 108	Harbison Blvd/Exit 103	4.47	- 12/17/2015
New Hampshire	I-89	I-93	Stickney Hill Rd/Exit 3	3.54	07/10/2016 - 07/24/2016
	I-93	I-393/US-202/US-4/Exit 15	Hackett Hill Rd/Exit 11	15.82	
	I-93	NH-28/Rockingham Rd/Exit 5	NH-102/Nashua Rd/Exit 4	3.63	
North Carolina	I-240	US-70/Charlotte St/Exit 5B	US-23/US-19/Exit 3	2.23	12/16/2016
	I-40	NC-191/Exit 47	US-23/US-19/Exit 44	2.56	-
	I-26	I-40/ Exit 46 A/US 74	I-26/Exit 37	14.43	12/26/2016



# Data Selection

**Road type:** Freeway

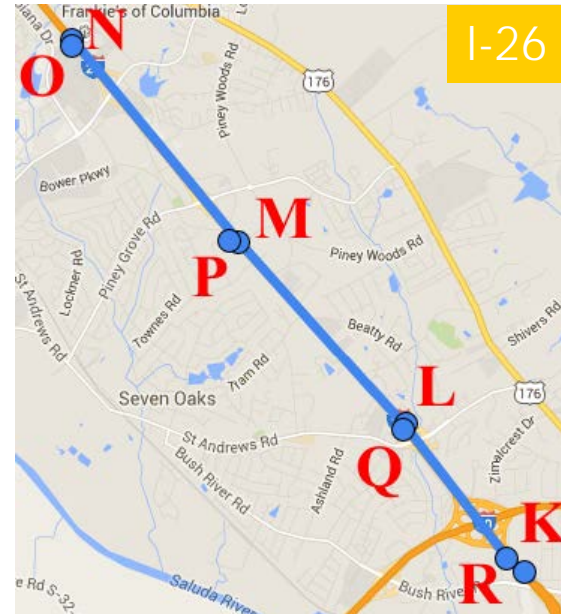
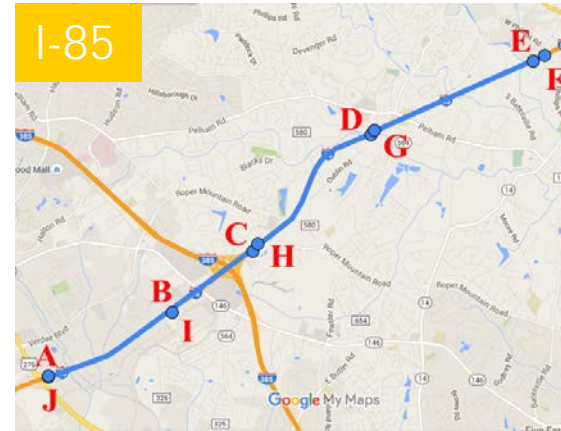
**Location:** South Carolina,  
New Hampshire, North Carolina

**Direction:** both directions

**Time:** 2 weeks for each state

**Segment length:** 1~3.5 mile

South Carolina



CASE STUDY

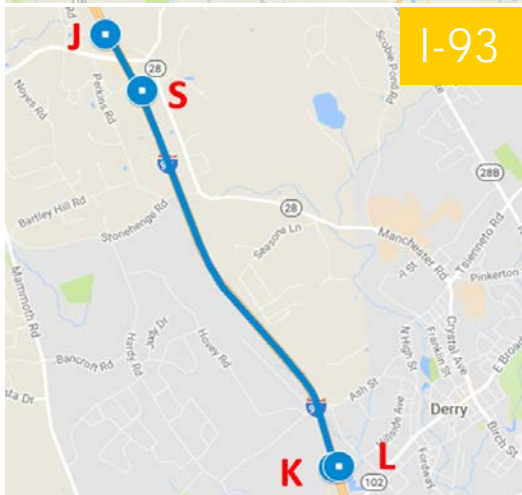
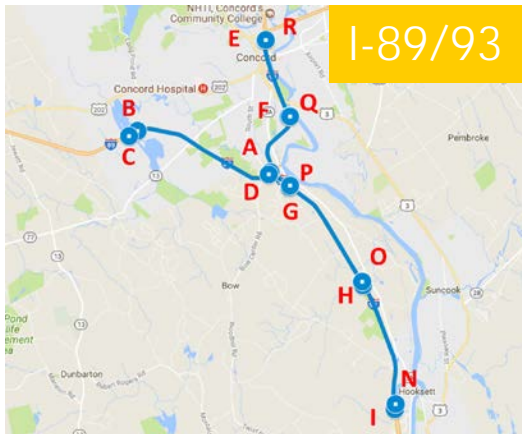


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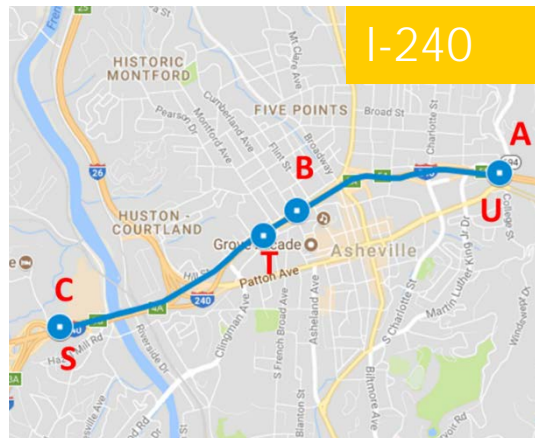


## Data Selection

New Hampshire

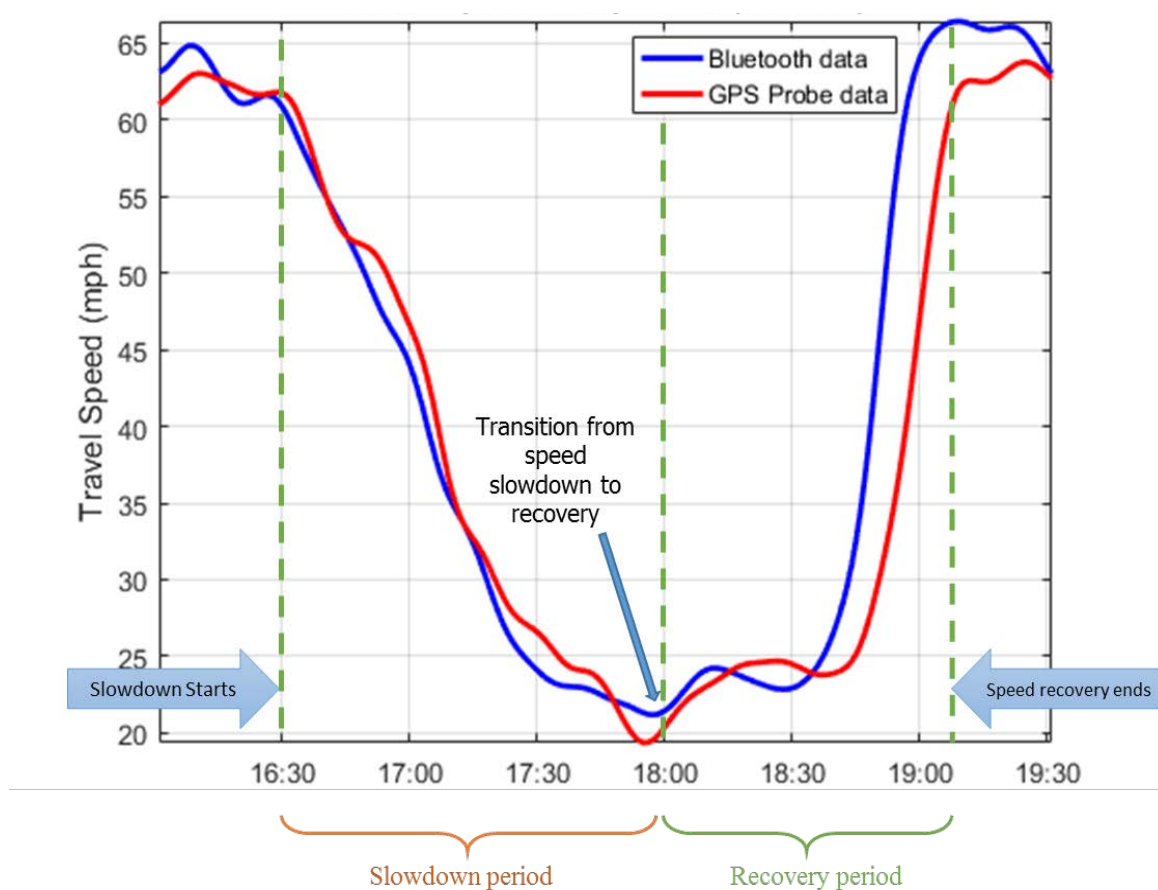


North Carolina

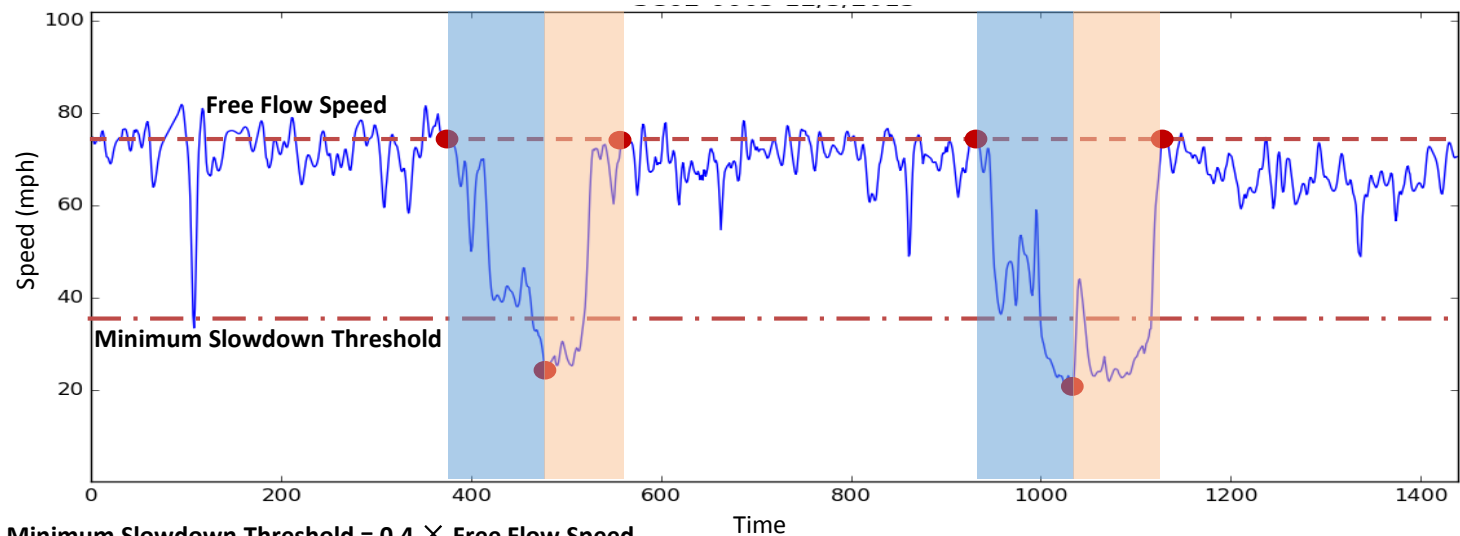


# Data Preparation

## Capturing Slowdown and Recovery Episodes



## Data Preparation: Automated Speed Pattern Recognition Filter (ASPRF)



Minimum Slowdown Threshold =  $0.4 \times \text{Free Flow Speed}$

State	# of paths	# of days	# of Slowdown and Recovery Episodes
South Carolina	14	15	72
New Hampshire	12	15	26
North Carolina	15	11	18
Total	41	41	116



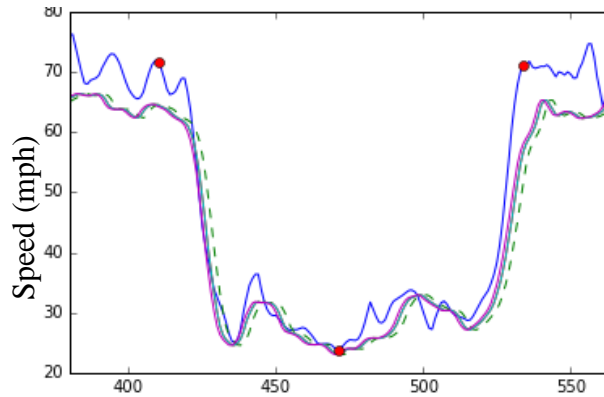
# Sample Result

South  
Carolina

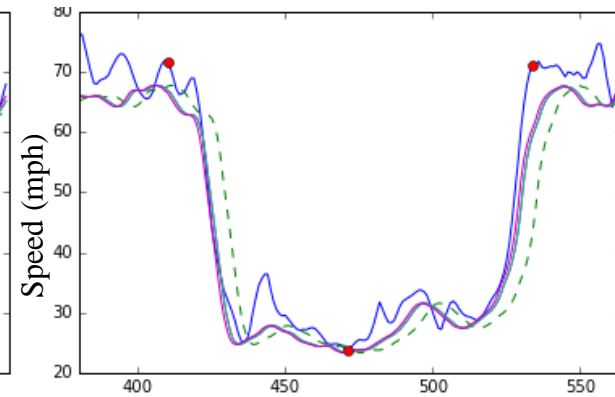
12/10/2015

Length: 2.3  
miles

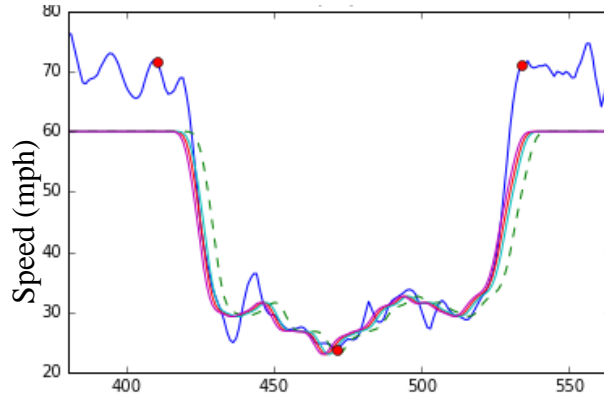
Data: 3  
vendors



(a) Vendor 1



(b) Vendor 2



(c) Vendor 3

## Legend

— REF	Reference (Bluetooth)
- - ORI	Original (GPS-probe data)
— AVD	Absolute Vertical Distance
— SVD	Squared Vertical Distance
— COR	Correlation coefficient

# Results

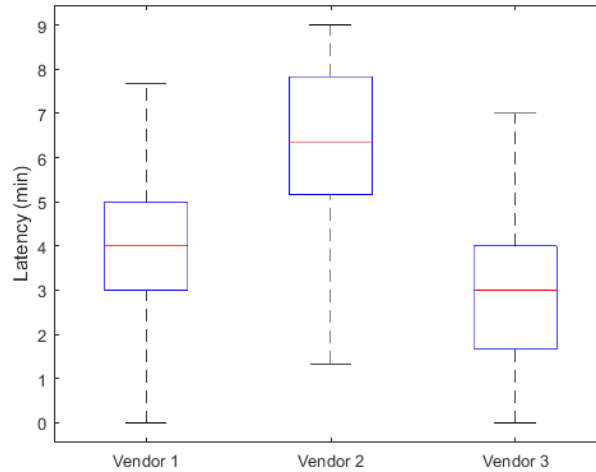
Average Latency for all segments over all periods (minute)

		Vendor 1				Vendor 2				Vendor 3			
		AVD	SVD	COR	Mean	AVD	SVD	COR	Mean	AVD	SVD	COR	Mean
SC	SRE	3.9	4.4	4.6	<b>4.3</b>	6.1	6.2	6.2	<b>6.2</b>	2.9	3.1	3.1	<b>3.0</b>
	SP	3.6	3.6	4.0	<b>3.7</b>	6.7	6.8	6.6	<b>6.7</b>	4.4	4.3	3.8	<b>4.2</b>
	RP	4.7	5.3	4.0	<b>4.7</b>	5.0	5.2	5.0	<b>5.1</b>	2.0	2.4	2.5	<b>2.3</b>
NH	SRE	3.3	3.4	3.6	<b>3.4</b>	5.6	6.0	6.4	<b>6.0</b>	2.3	2.5	2.7	<b>2.5</b>
	SP	3.3	3.2	3.2	<b>3.2</b>	7.0	7.0	6.7	<b>6.9</b>	3.5	3.0	3.2	<b>3.2</b>
	RP	4.0	4.2	3.9	<b>4.0</b>	3.6	3.7	4.7	<b>4.0</b>	2.9	3.5	2.6	<b>3.0</b>
NC	SRE	3.5	4.1	4.1	<b>3.9</b>	7.3	7.8	7.3	<b>7.5</b>	3.2	3.2	2.7	<b>3.0</b>
	SP	4.6	4.6	3.6	<b>4.2</b>	7.7	7.8	7.4	<b>7.6</b>	3.2	2.9	2.5	<b>2.9</b>
	RP	3.4	3.7	4.1	<b>3.7</b>	5.9	6.5	6.8	<b>6.4</b>	3.2	3.1	3.8	<b>3.4</b>

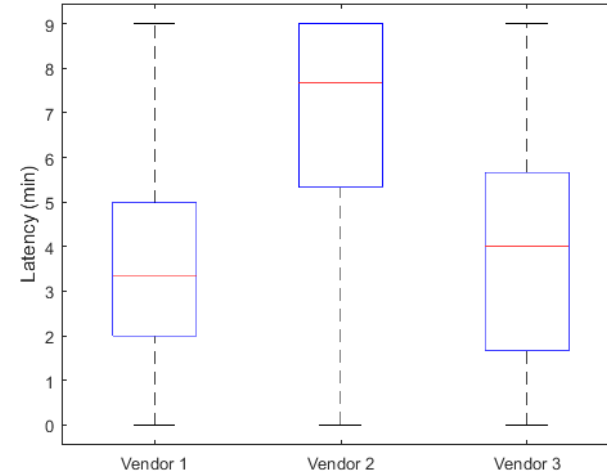
SC: South Carolina, NH: New Hampshire, NC: North Carolina; AVD: Absolute vertical distance; SVD: Squared vertical distance; COR: correlation coefficient; SRE: Slowdown and recovery episode, SP: Slowdown period, RP: recovery period

# Results

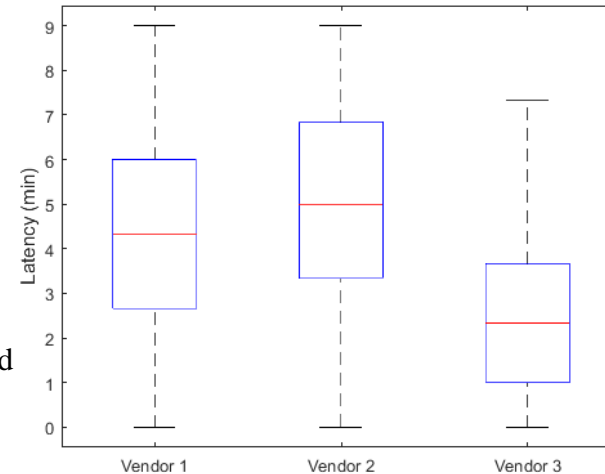
## Latency comparison between speed slowdown and recovery periods



(a) SRE



(b) SP



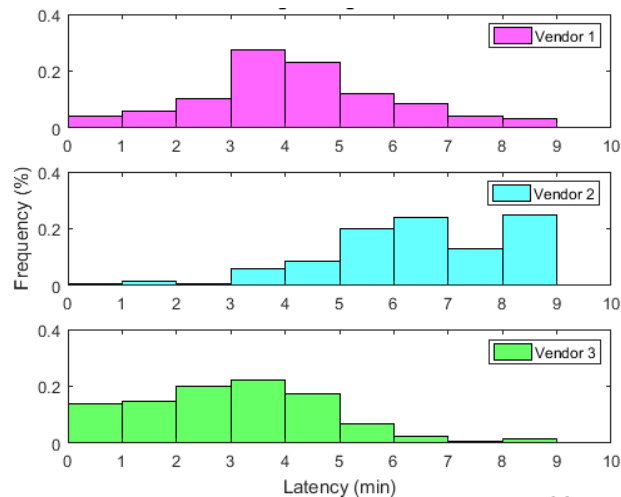
(c) RP

- ✓ Comparison results vary from vendor to vendor.
- ✓ Latency is different during slowdown and recovery.

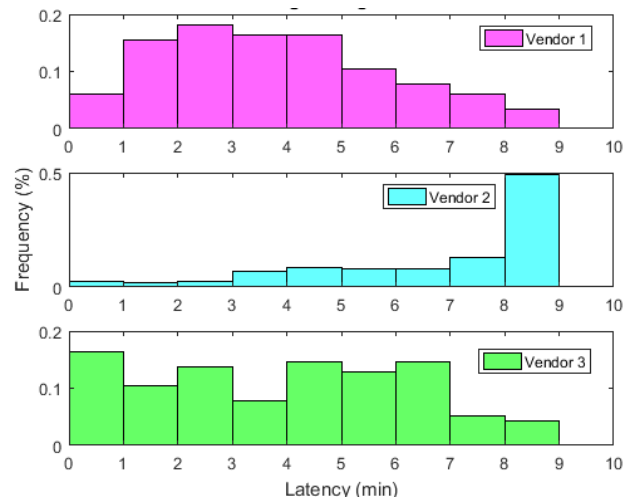
**Note:** whiskers represent the 1.5 interquartile range of the lower and upper quartiles, corresponding to approximately  $\pm 2.7$  times standard deviation and 99.3 percent coverage if the latency is normally distributed.

# Results

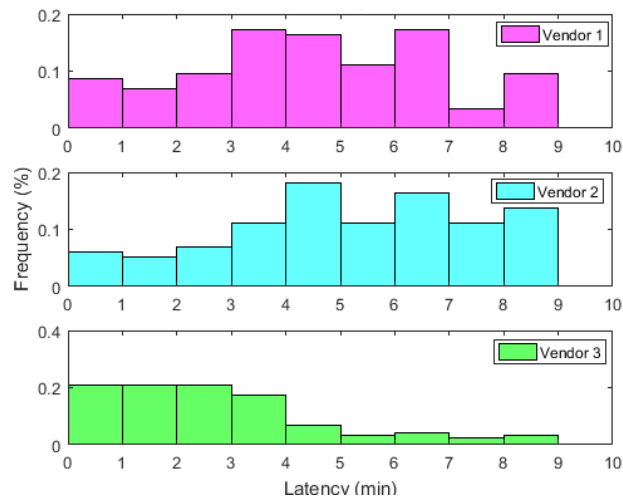
## Latency histogram



(a) SRE



(b) SP



(c) RP



## Result

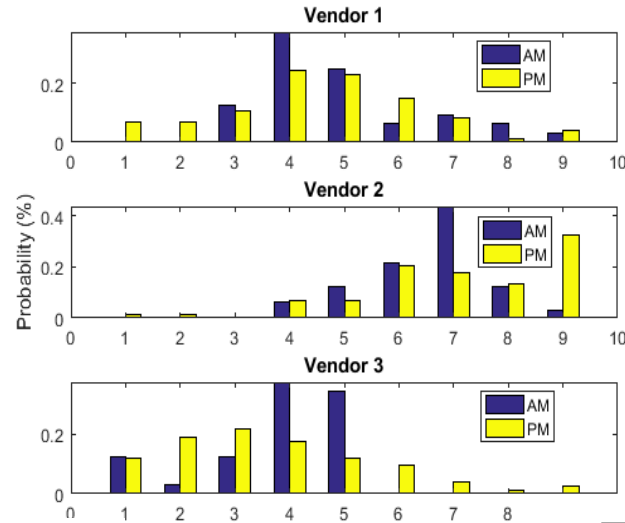
Is difference in probe data latency statistically significant between pair of vendors?

P-value	t-stat			Chi-square		
	Vendor 1	Vendor 2	Vendor 3	Vendor 1	Vendor 2	Vendor 3
Vendor 1		-9.370	4.729		2.685	0.598
Vendor 2	0.000		14.185	0.975		7.454
Vendor 3	0.000	0.000		1.000	0.590	

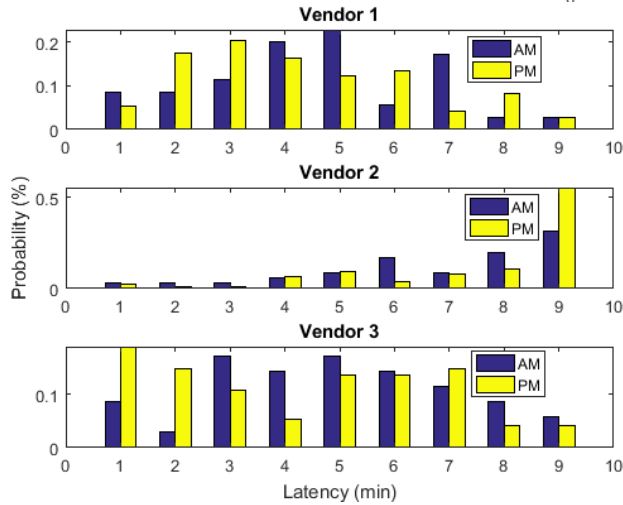
- ✓ Statistically speaking, average latency among vendors is different.
- ✓ The latency distribution is statistically independent among vendors.

## Result

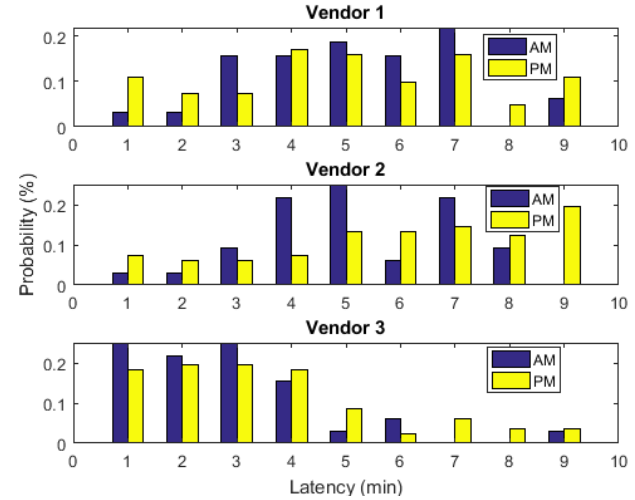
### Time of the day



(a) SRE

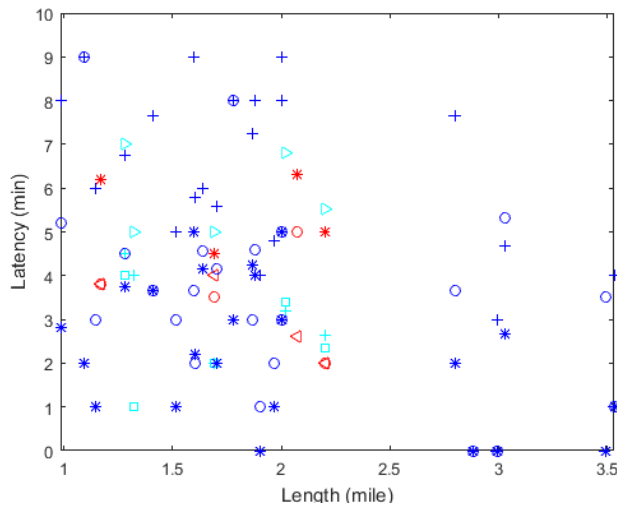


(b) SP

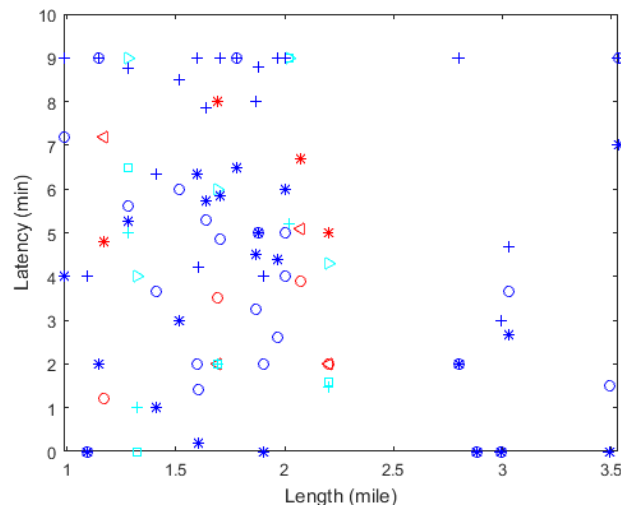


(c) RP

# Result Segment length

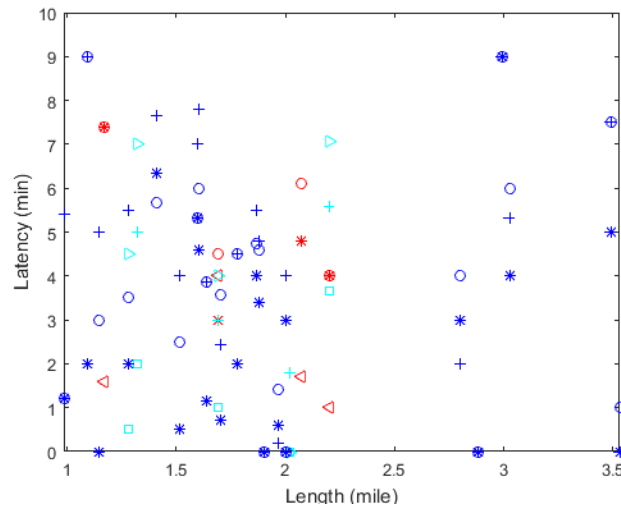
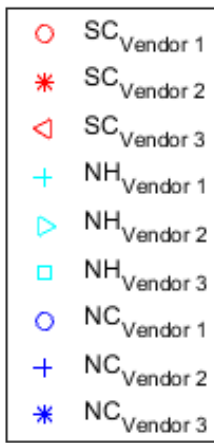


(a) SRE



(b) SP

✓ There is no strong relationship between the segment length and latency for all vendors.



(c) RP

# ConclusionS

- Across all vendors and for all tested freeway segments, average latency is found to be **4.4** minutes with standard deviation of 2.3 minutes;
- Average latency is statistically different among vendors;
- No strong correlation between latency and time of the day, and also latency and segment length were found.
- Instead of interpreting the latency as a single number, distribution of latency should be measured and evaluated

## Future Research

- Investigating the latency of GPS-probe data on signalized arterials.
- Studying potential impact of traffic volume on latency of probe data.
- Keep analyzing more cases in future to study long time trend of latency improvement for different vendors
- Understanding implications of the latency and its distribution on real-time applications and exploring solutions to compensate for latency

# Thank you Q & A

## **Masoud Hamedi\***

Senior Research Scientist  
Center for Advanced Transportation Technology  
University of Maryland  
5000 College Ave  
College Park, MD 20740  
Email: masoud@umd.edu | Phone: 301-405-2350

## **Zhongxiang Wang**

Graduate Student  
Department of Civil & Environmental Engineering  
University of Maryland  
Email: zxwang25@umd.edu

## **Elham Sharifi**

Faculty Research Assistant  
Center for Advanced Transportation Technology  
University of Maryland  
Email: esharifi@umd.edu

## **Stanley Young**

Advanced Transportation and Urban Scientist  
National Renewable Energy Laboratory  
Email: stanley.young@nrel.gov



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